



## Student Question

MONTCOMERY MIDDLE SCHOOL, SKILLMAN, NEW JERSEY

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00:00:03,436 --> 00:00:05,806

>> Now guys I've got a very special treat for you.

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00:00:06,026 --> 00:00:11,476

We're now going to go into the International Space Station mission control room and speak

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00:00:11,476 --> 00:00:17,756

with Public Affairs Commentator, Kylie Clem and a robotics engineer, Jonathan Rogers.

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00:00:17,986 --> 00:00:19,406

Are you guys there in mission control?

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00:00:20,876 --> 00:00:22,686

>> Kylie Clem: Hello, we're here in mission control.

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00:00:22,686 --> 00:00:26,426

Welcome, we're glad you could join us today and we're happy to take questions.

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00:00:26,426 --> 00:00:28,326

I'd like to introduce Jonathan to you first.

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00:00:28,326 --> 00:00:30,636

Jonathan Rogers is a robotics engineer.

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00:00:31,136 --> 00:00:34,766

He works with Robonaut 2 and other robotics here on the ground.

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00:00:35,206 --> 00:00:38,296

Robonaut 2 as you mentioned is on board the International Space Station

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00:00:38,656 --> 00:00:40,566

which is controlled from this room.

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00:00:40,566 --> 00:00:45,176  
The team here is watching over the systems  
and following along with the six crew members

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00:00:45,176 --> 00:00:46,776  
who are living and working on board.

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00:00:47,366 --> 00:00:52,326  
So I'd like to talk to Jonathan first about  
his background and how he came to work at NASA.

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00:00:52,986 --> 00:00:53,446  
>> Jonathan Rogers: Hello.

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00:00:54,946 --> 00:00:56,366  
As we've said my name's Jonathan Rogers.

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00:00:56,366 --> 00:01:01,256  
I actually came to NASA through an  
outreach program that my current group.

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00:01:01,536 --> 00:01:06,056  
It was called First Robotics [phonetic] and it  
gives an opportunity for high school students

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00:01:06,416 --> 00:01:10,446  
to work with professional  
engineers, in my case NASA engineers

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00:01:10,906 --> 00:01:13,756  
to develop a robot to play a game each year.

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00:01:14,446 --> 00:01:18,446  
And that competition just started a couple of  
weeks ago so we're looking forward to that.

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00:01:19,676 --> 00:01:23,926  
Following participating in the First Robotics

program, I went to Texas A&M University

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00:01:23,926 --> 00:01:29,256  
where I got a degree in aerospace engineering  
and during that time I was able to take part

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00:01:29,316 --> 00:01:34,906  
in NASA's Cooperative Education Program  
which allowed me to spend semesters here

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00:01:34,906 --> 00:01:38,196  
at the Johnson Space Center working  
on robots and then I would take

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00:01:38,196 --> 00:01:40,606  
that knowledge and apply it to my classes.

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00:01:41,476 --> 00:01:45,766  
And then I've been full-time working on the  
Robonaut 2 project for the last four years.

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00:01:46,766 --> 00:01:49,456  
>> Kylie Clem: So how's it been  
like sending the Robonaut to space

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00:01:49,516 --> 00:01:51,236  
and then working with it in space?

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00:01:51,656 --> 00:01:53,266  
>> Jonathan Rogers: It's  
been an amazing opportunity.

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00:01:53,536 --> 00:01:57,556  
When we developed the project, we  
started in 2007 and it was a partnership

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00:01:57,606 --> 00:01:59,006  
with the General Motors Corporation.

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00:01:59,576 --> 00:02:04,476

We found out that a lot of the goals that we have match up with the goals they have in terms

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00:02:04,476 --> 00:02:07,016

of helping people through the use of advanced robotics.

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00:02:07,486 --> 00:02:12,026

So we began this project purely as a technology demonstration platform where we could try

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00:02:12,026 --> 00:02:17,386

out new things and really push the envelope of what robotics are capable of doing.

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00:02:18,196 --> 00:02:22,346

When we announced the project to the world in 2010, we were given the unique opportunity

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00:02:22,346 --> 00:02:27,266

to fly it onboard the International Space Station on STS-133

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00:02:27,566 --> 00:02:29,706

which was just about a year ago, last February.

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00:02:30,746 --> 00:02:36,766

And in August we began working with it and we're continuing to check out the robot

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00:02:36,836 --> 00:02:39,666

and make sure it traveled safely to space.

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00:02:40,496 --> 00:02:43,386

And we really look forward to the future in finding out what it can do to help astronauts.

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00:02:44,046 --> 00:02:45,296

>> Kylie Clem: So what have you had to do --

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00:02:45,296 --> 00:02:49,016

you work with the Robonaut here on earth  
for quite a while before it actually

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00:02:49,016 --> 00:02:51,776

to the space station and other robots also.

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00:02:51,866 --> 00:02:54,496

So now that it's onboard the space  
station what have you been going

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00:02:54,496 --> 00:02:56,256

through to make sure that it's working well?

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00:02:57,566 --> 00:03:01,976

>> Jonathan Rogers: So to begin we just turned  
on the robot and let it sit there for a couple

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00:03:01,976 --> 00:03:03,576

of hours onboard the space station.

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00:03:03,766 --> 00:03:09,246

During the time, here in the mission control  
center we watched data and you know we checked

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00:03:09,246 --> 00:03:11,536

out all the sensors aboard  
the robot to make sure

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00:03:11,536 --> 00:03:14,416

that they had successfully  
made the trip into space.

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00:03:15,126 --> 00:03:19,486

And we were also learning, you know, how to  
interact with the other crew members on board

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00:03:19,486 --> 00:03:22,406

and the other flight controllers  
here in mission control to,

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00:03:22,406 --> 00:03:24,516

you know, safely accomplish our goals.

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00:03:25,416 --> 00:03:28,736

Over the next couple of checkout  
activities we've begun moving the robot

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00:03:29,266 --> 00:03:33,056

so we exercise every single  
joint aboard the robot.

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00:03:33,606 --> 00:03:39,356

And we learn how it's different to operate it  
in space than we've been working with it here

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00:03:39,356 --> 00:03:40,786

on the ground for the last few years.

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00:03:41,236 --> 00:03:44,546

And while it may seem very, very  
similar there are subtle differences

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00:03:45,186 --> 00:03:46,966

that really change how you control a robot.

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00:03:47,706 --> 00:03:49,566

>> Kylie Clem: And what do you  
think it might be able to do

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00:03:49,566 --> 00:03:50,926

in the future onboard the space station?

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00:03:51,196 --> 00:03:56,326

>> Jonathan Rogers: So some of the tasks that  
we're really going for are things that are dull

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00:03:56,326 --> 00:03:58,666

or boring for the crew, that  
take up a lot of their time.

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00:03:59,056 --> 00:04:03,356

For example we would love to have  
the robot to be able to clean.

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00:04:04,006 --> 00:04:08,706

The crew devotes a significant portion of  
their time on the weekends to just cleaning

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00:04:08,706 --> 00:04:13,576

up around the space station that way it's nice  
and tidy and you know it's a good place to live.

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00:04:13,786 --> 00:04:18,226

So if we can have a robot go take care of  
some of those tasks and you know off load it

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00:04:18,226 --> 00:04:22,566

from the crew, they could either have  
more free time or more time to spend

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00:04:22,566 --> 00:04:24,606

on different science experiments.

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00:04:25,536 --> 00:04:26,586

>> Kylie Clem: That sounds good.

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00:04:26,586 --> 00:04:31,436

Well, we'll go ahead and start  
with questions from the students.

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00:04:31,846 --> 00:04:32,486

>> Questions?

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00:04:32,546 --> 00:04:38,986

What questions do you have about the man who  
actually was instrumental in building Robonaut?

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00:04:38,986 --> 00:04:39,846  
Go ahead, nice and loud.

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00:04:40,016 --> 00:04:42,066  
>> Will you ever add legs to Robonaut?

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00:04:42,846 --> 00:04:44,856  
>> Jonathan Rogers: Yes, we're actually working on legs right now.

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00:04:44,856 --> 00:04:48,456  
We've got a pair of them in our lab here at the Johnson Space Center.

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00:04:49,236 --> 00:04:53,556  
And we're learning how to control those here on the ground before we send them to space.

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00:04:54,926 --> 00:05:00,876  
But the Robonaut is unique in that we can suit the lower body to the task at hand.

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00:05:00,876 --> 00:05:06,816  
So if we were to send Robonaut to a planet as we go and explore the solar system,

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00:05:07,066 --> 00:05:12,626  
we might find that like an off roader type of vehicle might be suitable for the lower base.

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00:05:13,296 --> 00:05:15,916  
You know climbing around on space station we've determined

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00:05:15,916 --> 00:05:19,586  
that two legs will be the best way to get around.

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00:05:20,766 --> 00:05:23,106

And you know that might change as we go outside the space station

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00:05:23,106 --> 00:05:32,926

to help astronauts with space walks.

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00:05:33,046 --> 00:05:33,696

>> Go ahead Stephanie [phonetic].

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00:05:33,696 --> 00:05:34,256

Nice and loud.

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00:05:34,456 --> 00:05:35,726

>> Stephanie: What [inaudible] Robonaut's helmet?

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00:05:37,746 --> 00:05:41,346

>> Jonathan Rogers: Inside Robonaut's helmet are actually five cameras.

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00:05:41,906 --> 00:05:45,686

We've got two cameras that are used by a human operator.

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00:05:46,516 --> 00:05:51,876

One of the modes we have to control Robonaut is where a person puts on virtual reality gear.

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00:05:51,876 --> 00:05:57,636

So you wear a headset and put on gloves and the robot will actually mimic your motions.

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00:05:58,686 --> 00:06:02,546

So we have cameras in there that are used for teleoperation

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00:06:02,786 --> 00:06:07,006

and then we also have two more cameras that are used for machine vision.

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00:06:07,466 --> 00:06:13,226  
Robonaut is programmed to identify things in its environment and we use those cameras to do that.

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00:06:13,686 --> 00:06:17,656  
They're really high resolution and allows the robot to see very good.

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00:06:17,656 --> 00:06:23,466  
And then finally we have an infrared camera which allows the robot

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00:06:23,466 --> 00:06:28,286  
to get a sense of depth in front of it.

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00:06:31,056 --> 00:06:31,886  
>> Nice. More questions?

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00:06:33,156 --> 00:06:34,856  
Go ahead Emily [phonetic], nice and loud.

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00:06:35,096 --> 00:06:36,216  
>> Emily: What's the robot power [inaudible]?

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00:06:38,536 --> 00:06:39,876  
>> Jonathan Rogers: So right now we're getting power

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00:06:39,876 --> 00:06:42,436  
from the International Space Station itself.

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00:06:43,676 --> 00:06:45,786  
We get power off the solar rays.

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00:06:45,786 --> 00:06:48,946  
That's you know passed through a number of systems before it gets to the robot.

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00:06:50,006 --> 00:06:54,496

Inside the robot's backpack we have power conversion that turns

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00:06:54,496 --> 00:06:58,056

into the different voltages that the robot needs to run.

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00:06:58,946 --> 00:07:04,436

One of the things that we're working on as we develop legs is also a large battery backpack.

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00:07:04,956 --> 00:07:11,946

That way it won't have to be plugged in all the time.

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00:07:12,046 --> 00:07:12,786

>> Go ahead, nice and loud.

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00:07:12,786 --> 00:07:16,536

>> How many people are needed to make a robot?

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00:07:17,666 --> 00:07:20,736

>> Jonathan Rogers: So to build Robonaut we had a team of about 25 people.

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00:07:21,176 --> 00:07:25,646

So it's pretty small but as we've gone through the process to send it to space,

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00:07:25,646 --> 00:07:27,356

we've had to bring in a lot more experts.

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00:07:27,356 --> 00:07:29,566

You know we're very good at designing robots.

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00:07:29,636 --> 00:07:33,926

We don't know anything about how to prepare them for space flight and there are experts here

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00:07:33,926 --> 00:07:37,406

at the Johnson Space Center  
who specialize in that.

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00:07:37,716 --> 00:07:41,936

Those folks work on things from  
making sure that we're compatible

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00:07:41,936 --> 00:07:46,386

with the power system onboard space  
station and making sure that we don't put

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00:07:46,386 --> 00:07:50,376

out any harmful radio waves that might interfere  
with other experiments on space station.

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00:07:50,776 --> 00:07:55,026

And then one of the biggest surprises we had  
was that we had to change the robot's suit.

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00:07:55,536 --> 00:08:00,636

The clothes that we had put on Robonaut we're  
actually too flammable to be considered safe

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00:08:00,636 --> 00:08:02,736

for space station so we had  
to make that change as well.

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00:08:03,596 --> 00:08:06,856

And you know we brought in the right folks from  
here at the Johnson Space Center to help us.

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00:08:07,516 --> 00:08:14,986

Now I'd say we probably have between 75 and 100  
people working on Robonaut at least part-time.

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00:08:18,096 --> 00:08:19,656

>> Wow. Good, nice and loud.

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00:08:19,906 --> 00:08:22,386

>> How did you guys get the idea for Robonaut?

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00:08:23,086 --> 00:08:28,976

>> Jonathan Rogers: So the Robonaut project started in 1997 with a goal of designing a robot

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00:08:29,386 --> 00:08:31,176

to help astronauts on space walks.

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00:08:31,716 --> 00:08:36,026

As astronauts were building the International Space Station there were many times

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00:08:36,026 --> 00:08:41,246

where identified you know a need for an assistant or a surrogate to go out

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00:08:41,396 --> 00:08:45,026

and help astronauts do different tasks.

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00:08:45,966 --> 00:08:48,516

So we've been working on the robot ever since

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00:08:48,516 --> 00:08:53,596

and this is Robonaut 2 that's onboard the space station which is our second generation.

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00:08:54,026 --> 00:08:58,366

>> Go ahead, nice and loud.

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00:08:58,686 --> 00:09:01,796

>> What materials or tools did you use to make [inaudible] Robonaut?

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00:09:02,826 --> 00:09:03,666

>> Jonathan Rogers: That's a very good question.

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00:09:03,756 --> 00:09:07,006

So primarily it's aluminum.

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00:09:07,066 --> 00:09:12,736

In certain places we have steel where we needed a stronger material and then we also have a lot

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00:09:12,736 --> 00:09:17,336

of plastic where, you know, we didn't need as much as strength in an area

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00:09:17,336 --> 00:09:21,426

but you wanted electronics or something to be protected.

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00:09:21,576 --> 00:09:24,116

For example, the helmet is plastic.

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00:09:29,086 --> 00:09:33,686

>> Go ahead, you have a question.

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00:09:34,306 --> 00:09:37,106

Anybody else?

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00:09:40,156 --> 00:09:40,896

Go ahead [inaudible].

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00:09:40,896 --> 00:09:45,876

>> What did you add to Robonaut 2 that Robonaut 1 didn't have?

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00:09:46,776 --> 00:09:47,786

>> Jonathan Rogers: Another great question.

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00:09:49,036 --> 00:09:54,936

With Robonaut 2 we concentrated on making the robot faster, stronger and smarter.

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00:09:55,816 --> 00:09:59,606

So in addition to changing the motors  
and things and allow the robot to move,

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00:09:59,606 --> 00:10:01,296

we also added a lot more sensing.

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00:10:01,636 --> 00:10:07,546

For example, the robot has sensors in each  
of its finger types that allow it to feel.

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00:10:08,096 --> 00:10:11,246

You can think of the technology  
as you know reaching

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00:10:11,246 --> 00:10:14,936

into your pocket to tell a nickel from a dime.

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00:10:14,936 --> 00:10:20,226

We have different cameras onboard that,  
like I said, have higher resolution

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00:10:20,226 --> 00:10:22,596

so we can see the environment  
in front of the robot better.

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00:10:23,856 --> 00:10:27,836

And then the control system, the software  
that runs the robot is also very different.

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00:10:27,836 --> 00:10:31,086

You know our partnership with GM we found

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00:10:31,086 --> 00:10:34,506

out that we want robots to  
work very close to people.

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00:10:35,006 --> 00:10:40,686

And traditional robotics on assembly lines you  
have cages and a number of different things

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00:10:40,686 --> 00:10:43,716

to keep robots away from people  
so that people don't get hurt.

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00:10:46,046 --> 00:10:48,616

In our view of the way of robots  
and people should work together.

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00:10:49,116 --> 00:10:53,406

They'll be very close so we  
added sensing and programming

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00:10:54,136 --> 00:10:55,836

to allow the robot to work safely around people.

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00:10:55,986 --> 00:11:02,866

For example it can bump into  
you and not hurt you.

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00:11:03,066 --> 00:11:06,296

>> And learn to say excuse me.

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00:11:06,296 --> 00:11:07,236

[Laughter]

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00:11:07,236 --> 00:11:08,546

>> Jonathan Rogers: It actually can't talk yet.

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00:11:08,546 --> 00:11:10,336

That's one of the things  
that we haven't worked in.

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00:11:11,126 --> 00:11:13,186

We need to put some speakers in  
but we didn't have time to do

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00:11:13,186 --> 00:11:18,866

that before we launched it to Space Station.

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00:11:18,866 --> 00:11:19,166

[Crosstalk]

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00:11:19,166 --> 00:11:25,206

>> Did it go up on a separate mission or did it go with astronauts that we're going up?

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00:11:25,206 --> 00:11:27,806

Or did it go up by itself automatically?

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00:11:27,996 --> 00:11:31,586

>> Jonathan Rogers: It flew up as a payload on STS-133.

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00:11:32,576 --> 00:11:32,806

>> Right.

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00:11:33,046 --> 00:11:35,706

>> Jonathan Rogers: And there were astronauts aboard as well.

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00:11:36,296 --> 00:11:39,936

It was Discovery I believe.

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00:11:40,266 --> 00:11:41,426

>> Kylie Clem: Yeah the space shuttle Discovery.

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00:11:41,426 --> 00:11:43,076

>> Go ahead.

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00:11:43,936 --> 00:11:46,466

>> What does payload mean?

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00:11:47,026 --> 00:11:50,136

>> Payload means that supplies that are going up.

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00:11:50,136 --> 00:11:54,296

In other words, when they say they're bringing payload, they're bringing food.

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00:11:54,396 --> 00:11:55,566

They're bringing water.

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00:11:55,566 --> 00:11:59,196

They're bringing machinery, tools, correct?

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00:11:59,416 --> 00:11:59,976

Is that correct?

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00:12:00,066 --> 00:12:00,806

>> Jonathan Rogers: That's exactly right.

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00:12:01,886 --> 00:12:09,356

So we were packaged inside a protective box and lot of foam along with a number

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00:12:09,356 --> 00:12:15,956

of replacement supplies for Space Station since the shuttle program was coming to an end.

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00:12:17,196 --> 00:12:20,496

We were launching a number of different things that'll ensure

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00:12:20,496 --> 00:12:24,026

that the astronauts have what they need to continue operating Space Station safely.

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00:12:30,086 --> 00:12:32,096

>> This is a live picture here at mission control.

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00:12:32,096 --> 00:12:33,536

Go ahead. We'll let both of you, go ahead.

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00:12:33,706 --> 00:12:36,496

>> How long has the Robonaut been up in space?

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00:12:37,456 --> 00:12:39,216

>> Jonathan Rogers: It's been there almost a year.

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00:12:39,216 --> 00:12:46,686

STS-133 launched in February of 2011.

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00:12:46,876 --> 00:12:48,286

>> And one more month will be a year.

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00:12:48,286 --> 00:12:48,686

Go ahead Emily.

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00:12:48,686 --> 00:12:52,166

>> And what are the similarities between like the joints and things

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00:12:52,166 --> 00:12:54,436

like that on the Robonaut and humans?

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00:12:56,736 --> 00:12:57,786

>> Jonathan Rogers: Another great question.

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00:12:58,966 --> 00:13:03,116

So Robonaut has electric motors in each of its joints.

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00:13:04,366 --> 00:13:09,176

So where you have muscles that allow your arm to move, we do a little bit differently

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00:13:09,176 --> 00:13:11,536

but the resulting motion is still the same.

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00:13:11,966 --> 00:13:13,416

The hand is more similar though.

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00:13:14,026 --> 00:13:17,356

If you move your hand you can kind  
of feel muscles in your forearm move

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00:13:17,616 --> 00:13:23,926

as your fingers move and in  
Robonaut we have mechanical actuators

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00:13:23,956 --> 00:13:26,356

that pull tendons to move the fingers.

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00:13:26,356 --> 00:13:27,866

And that's exactly how the human hand is --

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00:13:28,076 --> 00:13:33,096

there's a lot we can learn about how to build a  
human shaped robot from the human body itself.

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00:13:35,706 --> 00:13:38,806

>> I think somebody else had their hand up.

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00:13:38,976 --> 00:13:39,546

Yeah go ahead [inaudible].

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00:13:40,086 --> 00:13:43,106

>> [Inaudible] well why do you need  
both human and robots up [inaudible]?

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00:13:45,436 --> 00:13:49,406

>> Jonathan Rogers: So like I mentioned  
earlier there's things that the crew has to do

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00:13:49,406 --> 00:13:52,986

that takes a lot of their time that, you know,  
maybe doesn't require their full attention.

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00:13:53,206 --> 00:13:56,616

For example, cleaning takes  
up a lot of their time.

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00:13:56,616 --> 00:14:02,186

So we can, you know, have a robot that maybe doesn't have to be as smart as a person

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00:14:02,976 --> 00:14:04,406

but can take care of those things.

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00:14:04,706 --> 00:14:11,726

A couple of other ways that we anticipate using a Robonaut include being a surrogate

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00:14:11,726 --> 00:14:12,326

for astronaut.

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00:14:12,326 --> 00:14:15,816

So think of a mission that might be kind of dangerous

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00:14:15,816 --> 00:14:17,776

if we're exploring a planet and there's somewhere new.

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00:14:18,236 --> 00:14:22,786

Maybe you don't want to send an astronaut down a cave or something that could be dangerous

225

00:14:22,846 --> 00:14:24,056

but you kind of want to know what's down there.

226

00:14:24,576 --> 00:14:29,046

If you send a robot and something bad happens, you lose a Robonaut

227

00:14:29,386 --> 00:14:32,296

but the astronauts are still okay and that's what we really care about.

228

00:14:33,406 --> 00:14:37,836

Additionally we want to use Robonaut to help setup for space walks.

229

00:14:38,526 --> 00:14:42,616

A lot of time that astronauts use on a space walk where they go outside the space station

230

00:14:42,616 --> 00:14:47,356

to do a maintenance activity or assemble something is spent setting up.

231

00:14:47,836 --> 00:14:50,916

If you could have a robot go out there and do it ahead of time for them,

232

00:14:51,296 --> 00:15:01,976

they can devote more time to their task at hand.

233

00:15:02,056 --> 00:15:03,006

>> Go ahead sweetheart, nice and loud.

234

00:15:03,096 --> 00:15:04,656

>> Have there been any issues yet?

235

00:15:06,476 --> 00:15:10,036

>> Jonathan Rogers: Well, we're discovering that there are differences

236

00:15:10,036 --> 00:15:14,036

in between how we [inaudible] the robot on the ground and how it's operating in space.

237

00:15:14,606 --> 00:15:19,956

For example, you don't have as much friction in some of the joints.

238

00:15:19,956 --> 00:15:25,116

It's less resistance as you try to move the robot because there's no gravity.

239

00:15:26,216 --> 00:15:31,076

So little things like that we're learning  
and we're making adjustments as we go.

240

00:15:40,546 --> 00:15:42,116

>> Okay sounds good.

241

00:15:42,656 --> 00:15:43,946

I'll give you late passes.

242

00:15:44,576 --> 00:15:47,476

I think we're almost finished anyway.

243

00:15:47,476 --> 00:15:47,706

So --

244

00:15:47,956 --> 00:15:51,706

>> And if you guys have any  
additional questions,

245

00:15:51,706 --> 00:15:53,936

for example about the Space Station itself

246

00:15:53,936 --> 00:15:57,606

or mission control I believe Kylie  
would be able to answer those as well.

247

00:15:57,876 --> 00:16:02,966

>> Do you have any questions for  
the woman who's here, Ms. Kylie?

248

00:16:02,966 --> 00:16:07,696

She can answer any questions about mission  
control and the people who are sitting --

249

00:16:07,976 --> 00:16:12,546

did you notice the people sitting  
at the desks and things like that?

250

00:16:12,546 --> 00:16:16,656

Do you have any questions for that group?

251

00:16:16,786 --> 00:16:18,276

Yeah I think we're okay.

252

00:16:18,276 --> 00:16:19,826

[Chuckles]

253

00:16:19,826 --> 00:16:21,256

>> All right wonderful.

254

00:16:21,446 --> 00:16:24,636

Well, Kylie and Jonathan I want to thank you guys for joining us today

255

00:16:24,986 --> 00:16:28,366

from inside the International Space Station flight control room.

256

00:16:28,686 --> 00:16:31,466

And boys and girls can we give them a good round of applause.

257

00:16:33,266 --> 00:16:34,066

>> Jonathan Rogers: Thank you.

258

00:16:34,376 --> 00:16:35,516

>> Thank you so much.

259

00:16:35,676 --> 00:16:36,116

>> Kylie Clem: Thank you.

260

00:16:36,116 --> 00:16:38,506

>> We have one final thing we'd like to say too.

261

00:16:38,506 --> 00:16:39,256

>> Okay.

262

00:16:39,256 --> 00:16:39,676

>> Group of students: Thank you [inaudible].

263

00:16:39,996 --> 00:16:42,716

>> Yeah thanks so much.

264

00:16:42,976 --> 00:16:44,096

>> Kylie Clem: You're welcome.

265

00:16:44,416 --> 00:16:46,986

>> Thank you very much for your time.

266

00:16:46,986 --> 00:16:50,666

I can't tell you how informative  
it was and you could tell

267

00:16:50,666 --> 00:16:52,836

by the questions the level of interests.

268

00:16:52,836 --> 00:16:55,506

And these are your future  
robototists [phonetic] right here.

269

00:16:55,596 --> 00:16:57,496

Thank you.

270

00:16:58,286 --> 00:17:03,586

>> And before we close students if you  
want to stay on the line I want to go